

## Contents

5.1	Introduction to Laplace Transforms . . . . .	2
5.1.1	The Laplace Transform . . . . .	2
5.1.2	Existence of the Laplace Transform . . . . .	5
5.1.3	The Inverse Laplace Transform and Uniqueness . . . . .	6
5.2	Laplace Transform Pairs . . . . .	7
5.2.1	Shift Theorems . . . . .	10
5.2.2	Inverse transforms . . . . .	11
5.2.3	Laplace transforms of derivatives . . . . .	12
5.3	The Method of Partial Fractions . . . . .	14
5.4	Laplace Transforms of Periodic Functions and System Transfer Functions . .	17
5.4.1	Periodic Functions . . . . .	17
5.4.2	System Transfer Functions . . . . .	19
5.6	Convolution . . . . .	21
5.7	The Delta Function and Impulse Response . . . . .	22

## 5.1 Introduction to Laplace Transforms

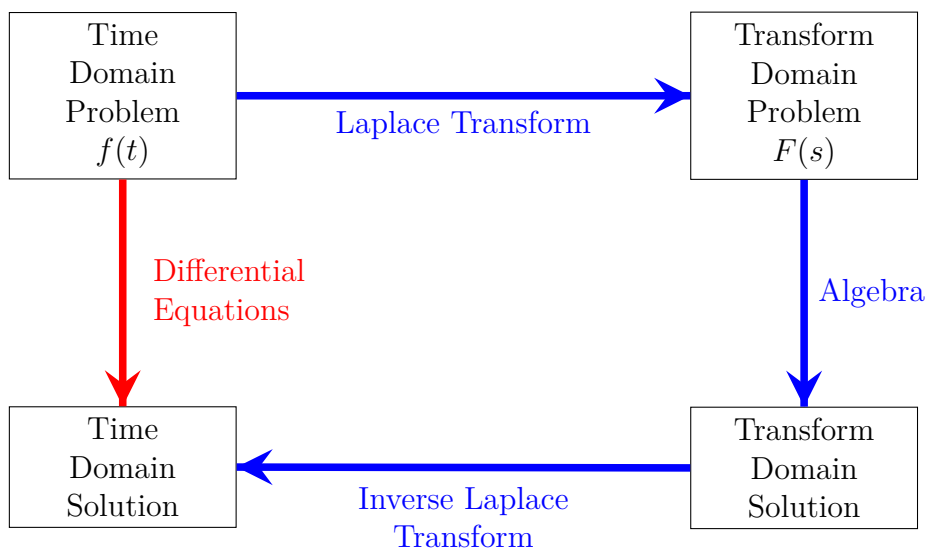
### 5.1.1 The Laplace Transform

When we are looking at problems involving Laplace Transforms there are always 2 domains to which you need to pay attention.

1. The time domain: variable ( $t$ )
2. The transform domain: variable ( $s$ )

When you work problems you must be either entirely in the time domain or the the transform domain. As a general rule you DO NOT work in both domains at the same time.

This flow chart shows the two different ways to solve a differential equation. You can either take the direct route or you can take the Laplace Transform route.



All Laplace transform problems have 3 steps.

1. Laplace transform to make the problem algebraic (simpler).
2. Solve/simplify the transformed problem with algebra.
3. Inverse Laplace transform to find solution.

## Definition of Laplace Transform

**Definition 5.1.** Let  $f(t)$  be defined for  $t \geq 0$  and let  $s$  be a real number. Then the **Laplace transform** of  $f(t)$ , denoted  $\mathcal{L}\{f(t)\}$ , is the function  $F(s)$  defined by

$$\mathcal{L}\{f(t)\} = F(s) = \int_0^{\infty} e^{-st} f(t) dt, \quad (5.1)$$

for those values of  $s$  for which the improper integral converges.

**Example 5.1.1.** Find the Laplace transform of  $f(t) = 8$

**Solution:** Recall the definition of an improper integral. If  $g$  is integrable over the interval  $[a, T]$  for every  $T > a$ , then the improper integral of  $g$  over  $[a, \infty)$  is defined as

$$\int_a^{\infty} g(t) dt = \lim_{T \rightarrow \infty} \int_a^T g(t) dt. \quad (5.2)$$

We say that the improper integral converges if the limit in (5.2) exists; otherwise, we say that the improper integral diverges or does not exist. So when we integrate for a Laplace transform we use the limit definition of the improper integral.

$$\begin{aligned} \mathcal{L}\{8\} &= \int_0^{\infty} 8e^{-st} dt \\ &= \lim_{T \rightarrow \infty} \left( \frac{-1}{s} \right) [8e^{-st}]_0^T \\ &= \lim_{T \rightarrow \infty} \left( \frac{-1}{s} \right) [8e^{-sT} - 8] \\ &= \begin{cases} \frac{8}{s} & \text{for } s > 0 \\ \infty & \text{for } s < 0 \end{cases} \end{aligned}$$

Notice that if  $s < 0$  then  $e^{-sT}$  has a positive exponent and  $\lim_{T \rightarrow \infty} e^{-sT} = \infty$

So we have found the Laplace transform of  $f(t) = 8$ :

$$\mathcal{L}\{8\} = \frac{8}{s} \quad \text{for } s > 0$$

**Note:** Rather than using the limit for the improper integral we will realize that we are taking the limit but we will instead simply write

$$\int_0^{\infty} 8e^{-st} dt = \left( \frac{-1}{s} \right) [8e^{-st}]_0^{\infty}$$

**Example 5.1.2.** Find the Laplace transform of  $f(t) = t^2$

**Solution:** This integral will require integration by parts twice. We can also look it up on a table of integrals:

$$\int t^n e^{at} dt = \frac{t^n e^{at}}{a} - \frac{n}{a} \int t^{n-1} e^{at} dt$$

$$\begin{aligned}\mathcal{L}\{t^2\} &= \int_0^{\infty} t^2 e^{-st} dt \\ &= \left[ -\frac{t^2 e^{-st}}{s} - \frac{2te^{-st}}{s^2} - \frac{2e^{-st}}{s^3} \right]_0^{\infty} \\ &= \left[ \left( -\frac{t^2}{s} - \frac{2t}{s^2} - \frac{2}{s^3} \right) e^{-s(\infty)} + \frac{2}{s^3} \right] \\ &= \begin{cases} \frac{2}{s^3} & \text{for } s > 0 \\ \infty & \text{for } s < 0 \end{cases}\end{aligned}$$

$\mathcal{L}\{t^2\} = \frac{2}{s^3}, \quad \text{for } s > 0$
---

**Example 5.1.3.** Find the Laplace transform of  $f(t) = e^{at}$

**Example 5.1.4.** Find the Laplace transform of  $f(t) = e^{t^2}$

$$\begin{aligned}\mathcal{L}\{e^{t^2}\} &= \int_0^{\infty} e^{t^2} e^{-st} dt \\ &= \int_0^{\infty} e^{t^2-st} dt \\ &= \int_0^{\infty} e^{t(t-s)} dt\end{aligned}$$

This integral will always diverge because, for any  $s > 0$  the exponent  $t(t-s)$  is positive for  $t > s$ . This means that the Laplace Transform of  $f(t) = e^{t^2}$  DOES NOT EXIST.

### 5.1.2 Existence of the Laplace Transform

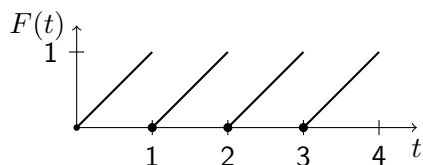
For a Laplace transform of a function  $f(t)$  to exist two things are required:

1. The function must be **piecewise continuous**:
  - Has a finite number of discontinuities on every finite interval.
  - The limit from the left and the limit from the right exist at all discontinuities.
2. The function must be **exponentially bounded**: There are constants  $M$  and  $a$  with  $M \geq 0$ , such that

$$|f(t)| < Me^{at}, \quad 0 \leq t < \infty$$

**Example 5.1.5.** The periodic saw tooth wave satisfies these conditions:

$$f(t) = t, \quad 0 \leq t < 1, \quad f(t+1) = f(t)$$



### Laplace Rules:

1. The Laplace transform is a linear operator: Suppose  $f(t) = C_1 f_1(t) + C_2 f_2(t)$

$$\mathcal{L}\{f(t)\} = C_1 \mathcal{L}\{f_1(t)\} + C_2 \mathcal{L}\{f_2(t)\}$$

2. If  $f(t) = f_1(t)f_2(t)$  then  $\mathcal{L}\{f(t)\}$  exists.

### 5.1.3 The Inverse Laplace Transform and Uniqueness

**Example 5.1.6.** Consider the two functions:

$$f_1(t) = e^{-t} \quad f_2(t) = \begin{cases} e^{-t} & \text{for } t \notin \mathbb{Z} \\ 0 & \text{for } t \in \mathbb{Z} \end{cases}$$

They both have the same Laplace transform:  $\mathcal{L}\{f_1(t)\} = \mathcal{L}\{f_2(t)\} = \frac{1}{s+1}$

So if we want to talk about the inverse Laplace transform of  $\frac{1}{s+1}$  we want to know what function has Laplace transform  $\frac{1}{s+1}$ . As we can see there can be more than one answer but, unless there is a compelling reason to do otherwise, we will always assume that the inverse Laplace transform is the continuous answer and we would say:

$$\mathcal{L}^{-1}\left\{\frac{1}{s+1}\right\} = e^{-t}$$

Once we know the Laplace transform we can put it in a table. See the text or the end of these notes for an incomplete list of Laplace transform pairs. If you look at row 4 of the table 1 you find that

$$\mathcal{L}\{e^{\alpha t}\} = \frac{1}{s-\alpha} \quad \text{and} \quad \mathcal{L}^{-1}\left\{\frac{1}{s-\alpha}\right\} = e^{\alpha t}$$

**Example 5.1.7.** Find the inverse Laplace transform of

$$F(s) = \frac{3}{s+2} + \frac{5}{s-2}$$

**Solution:**

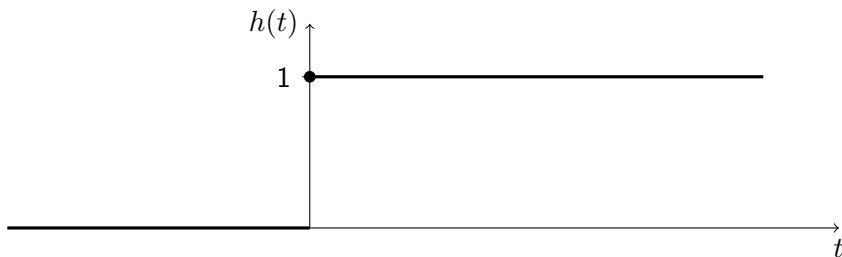
$$\begin{aligned} f(t) &= \mathcal{L}^{-1}\{F(s)\} \\ &= \mathcal{L}^{-1}\left\{\frac{3}{s+2}\right\} + \mathcal{L}^{-1}\left\{\frac{5}{s-2}\right\} \\ &= 3\mathcal{L}^{-1}\left\{\frac{1}{s+2}\right\} + 5\mathcal{L}^{-1}\left\{\frac{1}{s-2}\right\} \\ &= 3e^{-2t} + 5e^{2t} \end{aligned}$$

So  $\boxed{f(t) = 3e^{-2t} + 5e^{2t}}$

## 5.2 Laplace Transform Pairs

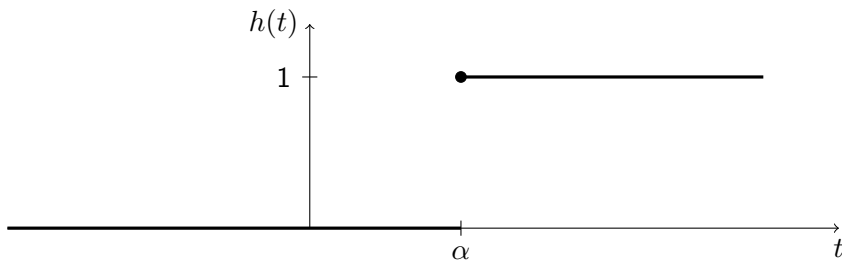
The unit step function or Heaviside step function is defined as follows:

$$h(t) = \begin{cases} 1 & t \geq 0 \\ 0 & t < 0 \end{cases}$$



Shifted by  $\alpha$

$$h(t - \alpha) = \begin{cases} 1 & t \geq \alpha \\ 0 & t < \alpha \end{cases}$$



**Example 5.2.1.** Find the Laplace transform of  $h(t)$  and  $h(t - \alpha)$ .

**Solution:**

$$\mathcal{L}\{h(t)\} = \int_0^{\infty} h(t)e^{-st} dt = \int_0^{\infty} e^{-st} dt = -\frac{1}{s} [e^{-st}]_0^{\infty}$$

$$\mathcal{L}\{h(t)\} = \frac{1}{s}, \quad s > 0$$

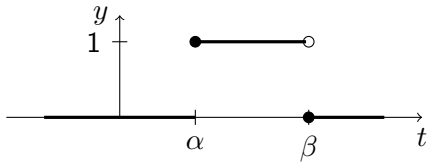
$$\mathcal{L}\{h(t - \alpha)\} = \int_0^{\infty} h(t - \alpha)e^{-st} dt = \int_{\alpha}^{\infty} (1)e^{-st} dt = -\frac{1}{s} [e^{-st}]_{\alpha}^{\infty}$$

$$= -\frac{1}{s} [0 - e^{-\alpha s}]$$

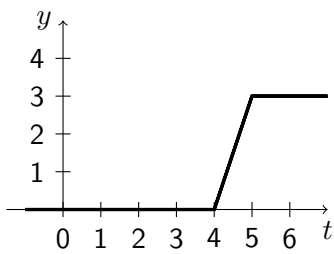
$$\mathcal{L}\{h(t - \alpha)\} = \frac{1}{s} e^{-\alpha s}, \quad s > \alpha$$

What is  $\mathcal{L}(1)$ ?

**Example 5.2.2.** Write the following graph as a single function.

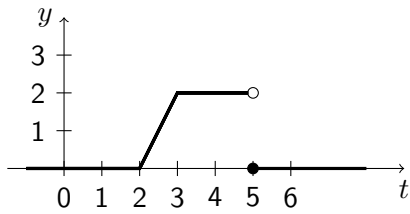


**Example 5.2.3.** Write the following graph as a single function.





**Example 5.2.4.** Write the following graph as a single function.



**Example 5.2.5.** Graph the function  $f(t) = \sin(t - 2\pi)h(t - 2\pi)$

**5.2.1 Shift Theorems**

1.  $\mathcal{L}\{e^{\alpha t} f(t)\} = F(s - \alpha)$

where  $\mathcal{L}\{f(t)\} = F(s)$  See #9 on table 1

2.  $\mathcal{L}\{f(t - \alpha)h(t - \alpha)\} = e^{-\alpha s} F(s)$

**Example 5.2.6.** Find the Laplace transform of  $f(t) = \sin(t - 2\pi)h(t - 2\pi)$

**Example 5.2.7.** Find the Laplace transform of  $f(t) = e^{2t} \cos(3t)$

**Example 5.2.8.** Find the Laplace transform of  $f(t) = 3t^2 + 2t + 1$

**Example 5.2.9.** Find the Laplace transform of  $f(t) = e^{4t}(3t^2 + 2t + 1)$

**5.2.2 Inverse transforms**

**Example 5.2.10.** Find the Laplace transform of  $f(t) = e^{3t-3}h(t-1)$

**Example 5.2.11.** Find the inverse Laplace transform of  $F(s) = \frac{3}{s} + \frac{24}{s^2}$

**Example 5.2.12.** Find the inverse Laplace transform of  $F(s) = \frac{2s-4}{(s-2)^2+9}$

**Example 5.2.13.** Find the inverse Laplace transform of  $F(s) = \frac{4s-6}{s^2-2s+10}$

**5.2.3 Laplace transforms of derivatives**

$$1. \mathcal{L}\{f'(t)\} = s\mathcal{L}\{f(t)\} - f(0) = sF(s) - f(0)$$

$$2. \mathcal{L}\{f''(t)\} = s^2F(s) - sf(0) - f'(0)$$

$$3. \mathcal{L}\left\{\int_0^t f(u) du\right\} = \frac{\mathcal{L}\{f(t)\}}{s} = \frac{F(s)}{s}$$

**Example 5.2.14.** Find the Laplace transform of the differential equation

$$\frac{dy}{dt} + 6y(t) + 9 \int_0^t y(\tau) d\tau = 1$$

and solve for  $Y(s)$ . Then use the inverse Laplace transform to find the solution to the equation  $y(t)$

**Example 5.2.15.** Solve the differential equation

$$y' + 4y = g(t), \quad y(0) = 0$$

where

$$g(t) = \begin{cases} 0, & 0 \leq t < 1 \\ 12, & 1 \leq t < 3 \\ 0, & 3 \leq t < \infty \end{cases}$$

### 5.3 The Method of Partial Fractions

	Denominator	Partial Fraction
Linear	$(s + a)$	$\frac{A}{s + a}$
Repeated Linear	$(s + a)^n$	$\frac{A_1}{s + a} + \frac{A_2}{(s + a)^2} + \cdots + \frac{A_n}{(s + a)^n}$
Quadratic	$s^2 + as + b$	$\frac{A_1s + A_2}{s^2 + as + b}$
Repeated Quadratic	$(s^2 + as + b)^2$	$\frac{A_1s + A_2}{s^2 + as + b} + \frac{A_3s + A_4}{(s^2 + as + b)^2}$

**Example 5.3.1.** Denominator is a product of distinct linear factors.

$$\frac{3x + 7}{x^2 + 6x + 5}$$

**Example 5.3.2.** Denominator is a product of linear factors, some of which are repeated.

$$\frac{3x^2 - 8x + 13}{(x + 3)(x - 1)^2}$$

**Example 5.3.3.** Denominator contains irreducible quadratic factors, none of which is repeated.

$$\frac{2x^2 + x - 8}{x^3 + 4x}$$

**Example 5.3.4.** Find  $\mathcal{L}^{-1} \left\{ \frac{s^2 + 4}{s^4 - s^2} \right\}$

**Example 5.3.5.** Find the inverse Laplace transform of

$$F(s) = \frac{50s}{(s+1)^2(s^2+4s+13)}$$

Note:

$$\mathcal{L}\{e^{\alpha t} t^n\} = \frac{n!}{(s-\alpha)^{n+1}}$$

$$\mathcal{L}\{e^{\alpha t} \sin \omega t\} = \frac{\omega}{(s-\alpha)^2 + \omega^2}$$

$$\mathcal{L}\{e^{\alpha t} \cos \omega t\} = \frac{s-\alpha}{(s-\alpha)^2 + \omega^2}$$



## 5.4 Laplace Transforms of Periodic Functions and System Transfer Functions

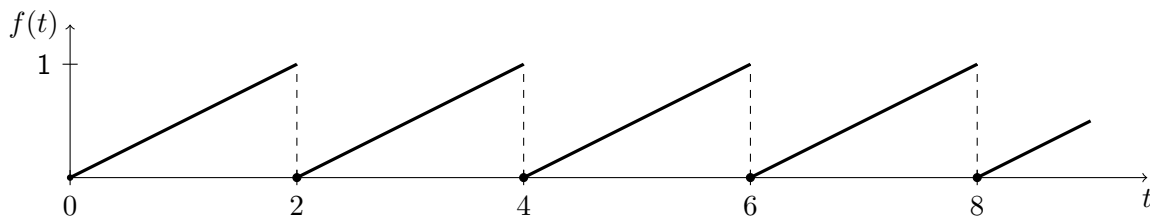
### 5.4.1 Periodic Functions

#### Laplace Transform of a Periodic Function

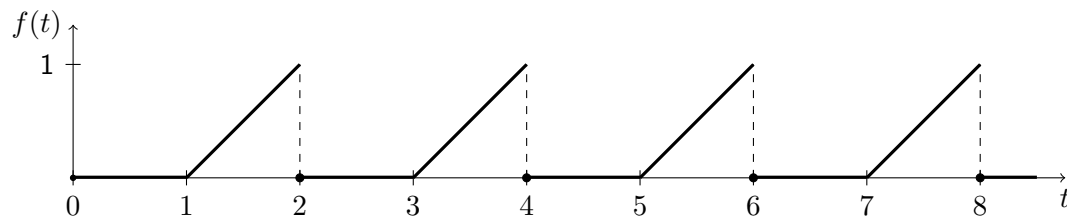
**Definition 5.2.** Let  $f(t)$  be a piecewise continuous periodic function defined on  $0 \leq t < \infty$  with period  $T$ . Then the Laplace transform of  $f(t)$  is the function defined by

$$\mathcal{L}\{f(t)\} = \frac{\int_0^T e^{-st} f(t) dt}{1 - e^{-sT}}, \quad s > 0 \quad (5.3)$$

**Example 5.4.1.** Find the Laplace transform of the function whose graph is shown



**Example 5.4.2.** Find the Laplace transform of the function whose graph is shown



### 5.4.2 System Transfer Functions

Consider the spring mass damper system we studied in Chapter 3. Given a mass  $m$ , a damper with damping coefficient  $\gamma$  and a spring with spring constant  $k$  then the system from equilibrium can be modeled by the differential equation

$$my'' + \gamma y' + ky = f(t), \quad t \geq 0, \quad y(0) = 0 \quad y'(0) = 0$$

where  $f(t)$  is some external force.

We can solve this using the techniques from chapter 3 or we can solve it using Laplace transforms by using

$$\mathcal{L}\{g'(t)\} = sG(s) - g(0)$$

$$\mathcal{L}\{g''(t)\} = s^2G(s) - sg(0) - g'(0)$$

$$\begin{aligned} \mathcal{L}\{my'' + \gamma y' + ky\} &= \mathcal{L}\{f(t)\} \\ m(s^2Y(s)) + \gamma(sY(s)) + kY(s) &= F(s) \\ Y(s) &= \frac{1}{ms^2 + \gamma s + k} F(s) \end{aligned}$$

We can think of  $\frac{1}{ms^2 + \gamma s + k}$  as a single item and call it  $\Phi(s) = \frac{1}{ms^2 + \gamma s + k}$ . Then our equation in the transform domain is simply

$$Y(s) = \Phi(s)F(s)$$

where  $\Phi(s)$  can be found from knowing the input  $F(s)$  and the output  $Y(s)$  and nothing else.

$$\Phi(s) = \frac{Y(s)}{F(s)} \tag{5.4}$$

$\Phi(s)$  is called the **system transfer function**.

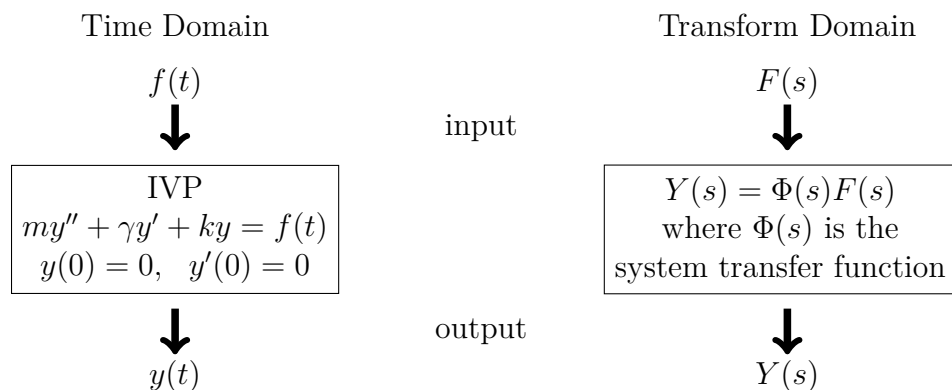


Figure 1: Two ways to solve a mechanical system. In the time domain or the Laplace domain

**Example 5.4.3.** Suppose we know we have the spring-mass-damper system

$$my'' + \gamma y' + ky = f(t) \quad y(0) = 0, \quad y'(0) = 0.$$

If we apply the Heaviside step function as the input forcing function  $f(t) = h(t)$  then the output is  $y(t) = \frac{1}{2} - \frac{1}{2}e^{-t} \cos t - \frac{1}{2}e^{-t} \sin t$ . Given a new input of  $\hat{f}(t) = e^{-2t}$ , what is the new output  $\hat{y}(t)$

## 5.6 Convolution

## 5.7 The Delta Function and Impulse Response

Table 1: A Brief Table Of Laplace Transform Pairs

$f(t), t \geq 0$	Laplace Transform $F(s)$
1. $h(t) = \begin{cases} 1 & t \geq 0 \\ 0, & t < 0 \end{cases}$	$\frac{1}{s}$ ( $s > 0$ )
2. 1	$\frac{1}{s}$ ( $s > 0$ )
3. $t^n, \quad n = 1, 2, 3, \dots$	$\frac{n!}{s^{n+1}}$ ( $s > 0$ )
4. $e^{\alpha t}$	$\frac{1}{s - \alpha}$ ( $s > \alpha$ )
5. $\sin \omega t$	$\frac{\omega}{s^2 + \omega^2}$ ( $s > 0$ )
6. $\cos \omega t$	$\frac{s}{s^2 + \omega^2}$ ( $s > 0$ )
7. $\sinh bt = \frac{e^{bt} - e^{-bt}}{2}$	$\frac{b}{s^2 - b^2}$ ( $s >  b $ )
8. $\cosh bt = \frac{e^{bt} + e^{-bt}}{2}$	$\frac{s}{s^2 - b^2}$ ( $s >  b $ )
9. $e^{\alpha t} f(t)$ , with $ f(t)  \leq M e^{at}$	$F(s - \alpha)$ $s > \alpha + a$
(10) - (13) are four special cases of (9)	
10. $e^{\alpha t} h(t)$	$\frac{1}{s - \alpha}$ ( $s > \alpha$ )
11. $e^{\alpha t} t^n, \quad n = 1, 2, 3, \dots$	$\frac{n!}{(s - \alpha)^{n+1}}$ ( $s > \alpha$ )
12. $e^{\alpha t} \sin \omega t$	$\frac{\omega}{(s - \alpha)^2 + \omega^2}$ ( $s > \alpha$ )
13. $e^{\alpha t} \cos \omega t$	$\frac{s - \alpha}{(s - \alpha)^2 + \omega^2}$ ( $s > \alpha$ )
14. $f(t - \alpha)h(t - \alpha), \quad (\alpha \geq 0),$ with $ f(t)  \leq M e^{at}$	$e^{-\alpha s} F(s)$ ( $s > a$ )
15. $h(t - \alpha), \quad \alpha \geq 0$	$\frac{e^{-\alpha s}}{s}$ ( $s > 0$ )
16. $f'(t)$ , with $f(t)$ continuous with $ f'(t)  \leq M e^{at}$	$sF(s) - f(0)$ $s > \max\{a, 0\}$

17. $f''(t)$ , with $f'(t)$ continuous with $ f''(t)  \leq Me^{at}$	$s^2 F(s) - sf(0) - f'(0)$	$s > \max\{a, 0\}$
18. $f^{(n)}(t)$ , with $f^{(n-1)}(t)$ continuous with $ f^{(n)}(t)  \leq Me^{at}$	$s^n F(s) - s^{n-1}f(0) - \dots$ $-sf^{(n-2)} - f^{(n-1)}(0)$	$s > \max\{a, 0\}$
19. $\int_0^t f(u) du$ , with $ f^{(n)}(t)  \leq Me^{at}$	$\frac{F(s)}{s}$	$s > \max\{a, 0\}$
20. $\int_0^t f(t-\lambda)g(\lambda) d\lambda$	$F(s) \cdot G(s)$	
21. $t \cos \omega t$	$\frac{s^2 - \omega^2}{(s^2 + \omega^2)^2}$	$(s > 0)$
22. $t \sin \omega t$	$\frac{2\omega s}{(s^2 + \omega^2)^2}$	$(s > 0)$
23. $\sin \omega t - \omega t \cos \omega t$	$\frac{2\omega^3}{(s^2 + \omega^2)^2}$	$(s > 0)$
24. $\omega t - \sin \omega t$	$\frac{\omega^3}{s^2(s^2 + \omega^2)^2}$	$(s > 0)$
25. $tf(t)$	$-F'(s)$	
26. $t^k f(t)$	$(-1)^k F^{(k)}(s)$	
27. $\delta(t-a)$	$e^{-as}$	$(s > 0)$

### For Periodic Functions:

Let  $f(t)$  be a piecewise continuous periodic function defined on  $0 \leq t < \infty$ , where  $f(t)$  has period  $T$ . Then

$$\mathcal{L}\{f(t)\} = \frac{\int_0^T e^{-st} f(t) dt}{1 - e^{-sT}}, \quad s > 0$$

### Convolution

$$(f * g)(t) = \int_0^t f(t-\lambda)g(\lambda) d\lambda$$

$$(f * g)(t) = \mathcal{L}^{-1}\{F(s)G(s)\}$$